

# DAGs and Bad Controls

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Core Empirical Research Methods

## Selection on observables again...

### Last Time

- ▶ Binary treatment  $D$ , potential outcomes  $(Y_0, Y_1)$ .
- ▶ Observed outcome  $Y = (1 - D)Y_0 + DY_1$ .
- ▶ Selection on observables:  $D \perp\!\!\!\perp (Y_0, Y_1) | \mathbf{X}$  for observed covariates  $\mathbf{X}$ .
- ▶ Overlap:  $0 < p(\mathbf{X}) < 1$ . (Recall that we can check this.)
- ▶ Regression Adjustment, Propensity Score weighting, Matching

### Elephant in the Room

We have completely ignored the question of what to include in  $\mathbf{X}$ .

# Which covariates should we adjust for?

## Identification

- ▶ Some choices of  $\mathbf{X}$  may satisfy  $D \perp\!\!\!\perp (Y_0, Y_1) | \mathbf{X}$  while others don't.
- ▶ If selection on observables assumption fails, we don't get the ATE / TOT.

## Efficiency

- ▶ There may be multiple choices of  $\mathbf{X}$  that satisfy selection on observables.
- ▶ But some may produce more efficient estimates of the ATE / TOT.

Today: focus on identification; use regression adjustment for simplicity.

# The Omitted Variables Bias (OVB) Formula<sup>1</sup>

- ▶ To keep things simple, assume a linear model with homogeneous effects:

$$Y = \alpha + \beta D + \gamma X + U, \quad \text{Cov}(D, U) = \text{Cov}(X, U) = \mathbb{E}(U) = 0.$$

- ▶ In other words:

$$Y_0 = \alpha + \gamma X + U, \quad Y_1 = Y_0 + \beta, \quad \text{ATE} = \text{TOT} = \beta$$

- ▶ What does a regression of  $Y$  on  $D$  identify?

$$\frac{\text{Cov}(D, Y)}{\text{Var}(D)} = \frac{\text{Cov}(D, \alpha + \beta D + \gamma X + U)}{\text{Var}(D)} = \beta + \gamma \frac{\text{Cov}(D, X)}{\text{Var}(X)}$$

- ▶ “Short” regression coefficient only equals  $\beta$  if  $\gamma = 0$  or  $\text{Cov}(D, X) = 0$ .

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<sup>1</sup>See, e.g., Section 3.2.2 of *Mostly Harmless Econometrics*.

## How *not* to interpret the OVB Formula.

- ▶ OVB Formula tells us *when* and *how* the coefficient on  $D$  differs depending on whether we include  $X$  in the regression.
- ▶ “Short” regression includes only  $D$ ; “Long” regression includes both  $D$  and  $X$ .
- ▶ “Short” and “Long” coefficients for  $D$  agree if:
  1.  $X$  does not help predict  $Y$  in the “Long” regression or
  2.  $X$  is uncorrelated with  $D$ .
- ▶ Only if we **assume** that the long regression is the true causal model does this tell us whether we need to adjust for  $X$ .

Bad Advice: "Adjust for any observed variable that is correlated with  $D$  and  $Y$ ."

## Example 1: A prototypical bad control.

```
set.seed(1693)
n <- 5000
d <- rbinom(n, 1, 0.4)
x <- rbinom(n, 1, 0.25 + 0.5 * d)
y <- x + rnorm(n)
mean(y[d == 1]) - mean(y[d == 0])
## [1] 0.523149
```

```
library(broom); library(tidyverse)
xtilde <- x - mean(x)
reg <- lm(y ~ d + x + d:xtilde)
tidy(reg) |> filter(term == 'd') |>
  select(estimate, std.error)

## # A tibble: 1 x 2
##   estimate std.error
##   <dbl>    <dbl>
## 1  0.0113    0.0343
```

$$\begin{aligned}\mathbb{E}[Y_1 - Y_0] &= \mathbb{E}[Y|D = 1] - \mathbb{E}[Y|D = 0] \\ &= \mathbb{E}[X|D = 1] - \mathbb{E}[X|D = 0] = 0.5\end{aligned}$$

# Why is $X$ a bad control?

## Intermediate Outcome

- ▶ Example 1:  $X$  is *itself* an outcome of  $D$  that *goes on* to cause  $Y$ .
- ▶ Adjusting for an intermediate outcome masks the true causal effect of  $D$ .
- ▶ E.g. randomized early childhood intervention causes college; college causes wage.
- ▶ In the simulation, 100% of the effect of  $D$  on  $Y$  goes through  $X$ .

## Common Advice

*Variables measured before the variable of interest [ $D$ ] was determined are usually good controls. In particular, because these variables were determined before the variable of interest, they cannot themselves be outcomes in the causal nexus.<sup>2</sup>*

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<sup>2</sup>From Section 3.2.3 of *Mostly Harmless Econometrics*, but similar statements are common.

## Example 2: This bad control *is not* an intermediate outcome.

```
library(mvtnorm)
R <- matrix(c(1, 0.5, 0.5, 1),
            2, 2)
errors <- rmvnorm(n, sigma = R)
u <- errors[,1]
v <- errors[,2]
x <- rbinom(n, 1, 0.5)
d <- 1 * ((-1 + 2 * x + v) > 0)
y <- -0.3 + d + u

mean(y[d == 1]) - mean(y[d == 0])

## [1] 1.511498
```

```
xtilde <- x - mean(x)
lm(y ~ d + x + d:xtilde) |>
  tidy() |>
  filter(term == 'd') |>
  select(estimate, std.error)

## # A tibble: 1 x 2
##   estimate std.error
##   <dbl>     <dbl>
## 1     1.90     0.0355
```



# Why is $X$ a bad control?

## Instrumental Variable

- ▶ Example 2:  $X$  is a valid instrument for the endogenous treatment  $D$ .
- ▶ But this is the **wrong** way to use an instrumental variable: should run IV.
- ▶ Adjusting for  $X$  soaks up the **exogenous** part of  $D$ , making the bias worse.<sup>3</sup>

```
library(AER)
ivreg(y ~ d | x) |> tidy() |> filter(term == 'd') |>
  select(estimate, std.error)
```

```
## # A tibble: 1 x 2
##   estimate std.error
##   <dbl>     <dbl>
## 1     1.01     0.0430
```

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<sup>3</sup>See [here](#) for a proof.

## “No causes in; no causes out.”<sup>4</sup>

### Feeling confused?

- ▶ How can we tell which variables to adjust for and which are bad controls?
- ▶ Is it simply a matter of “I know it when I see it”?

### Bad News

- ▶ Meaningful causal inference **always** requires assumptions, even in RCTs.
- ▶ Causal inference from observational data requires **even more** assumptions.

### Good News

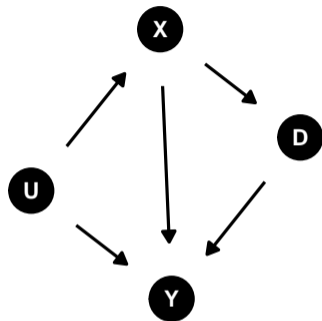
- ▶ If you make your assumptions explicit, there is a **definitive** solution.
- ▶ If it's possible to use selection-on-observables, find the correct **X**; if it's not possible, show why this is so.
- ▶ Free bonus: better intuition about bad controls.

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<sup>4</sup>Nancy Cartwright

## Graph Terminology

- ▶ **Graph**: set of **nodes** connected by **edges**.
- ▶ Two nodes are **adjacent** if connected by an edge.
- ▶ Edges can be **directed** (figure) or **undirected**.
- ▶ Directed edge points from **parent** to **child**.
- ▶ **Directed graph** has only directed edges.
- ▶ **Path**: sequence of connected vertices.
- ▶ **Directed Path**: a path that “obeys one-way signs”
- ▶ Directed path points from **ancestor** to **descendant**.
- ▶ **Cycle**: directed path that returns to starting node.
- ▶ **Acyclic Graph**: a graph without any cycles.



## Structural Causal Model

- ▶ Structural Equations:  $f = (f_d, f_x, f_y)$
- ▶ Exogenous "Errors":  $(U, V, W)$
- ▶  $P$  and  $f$  induce **observational dist** of Endogenous Variables:  $(D, X, Y)$

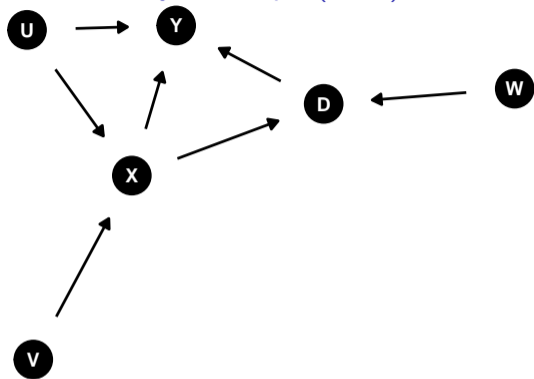
$$X \leftarrow f_x(U, V)$$

$$D \leftarrow f_d(X, W)$$

$$Y \leftarrow f_y(D, X, U)$$

$$(U, V, W) \sim P$$

## Directed Acyclic Graph (DAG)<sup>a</sup>



<sup>a</sup>We'd usually suppress  $W$  and  $V$ .

- ▶ Graphical causal model (DAG): "stylized" structural model (non-parametric)
- ▶ Directed edges encode **assumptions** about flow of causal influence or lack thereof.
- ▶ (Parent  $\rightarrow$  Child = **Direct Cause**); (Ancestor  $\rightarrow$  Descendant = **Potential Cause**)

# How Graphical Causal Models (DAGs) Can Help

## Key Point

DAGs encode **conditional dependence structure** under our modelling assumptions.

## Back Door Criterion

- ▶ Is it possible to learn the causal effect of  $D$  on  $Y$  via selection on observables?
- ▶ If so, which observed variables should we adjust for?

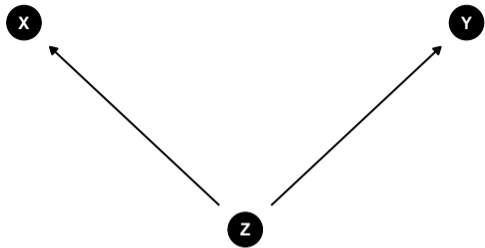
## Placebo Tests

- ▶ What conditional **independencies** between endog. variables does our model imply?
- ▶ Since these variables are observed, we can **partially test** our model.

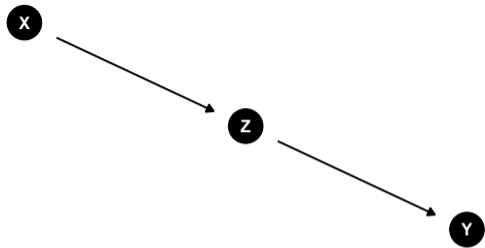
## Do-Calculus

Determine if causal effect of interest is non-parametrically identified **full stop**, whether by selection on observables, IV, or something else.

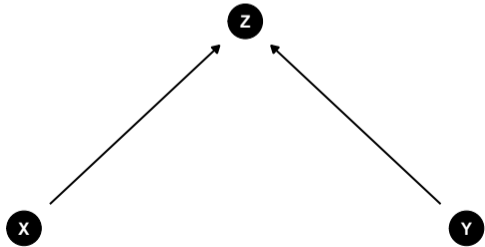
Fork



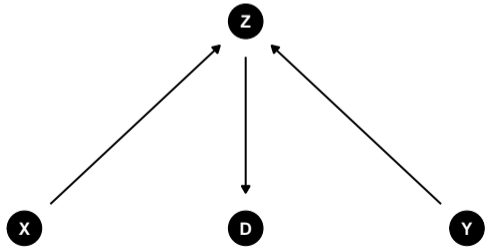
Pipe



Collider



Descendant



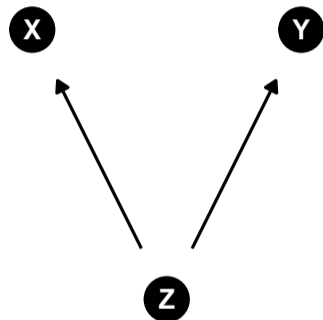
# The Fork: A Common Cause

## Fork Lemma

If  $Z$  is a common cause of  $X$  and  $Y$  and there is only one path between  $X$  and  $Y$ , then  $X \perp\!\!\!\perp Y | Z$ .

## So what?

- ▶  $X$  and  $Y$  are correlated even if neither causes the other.
- ▶ Adjusting for  $Z$  solves the problem: **blocks the path**.
- ▶  $Z$  = health status,  $X$  = hospital,  $Y$  = mortality.



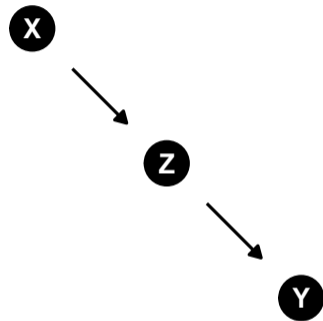
# The Pipe: A Mediator<sup>5</sup>

## Pipe Lemma

If there is only one directed path from  $X$  to  $Y$  and  $Z$  intercepts that path, then  $X \perp\!\!\!\perp Y | Z$ .

## So what?

- ▶ Adjusting for  $Z$  **blocks the path**, just like in the pipe.
- ▶ But if we want the causal effect of  $X$  on  $Y$ , this is **bad**.
- ▶ This is *precisely* example 1 from above.
- ▶  $X$  = childhood intervention,  $Z$  = college,  $Y$  = wage.



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<sup>5</sup>Also known as a “chain”.



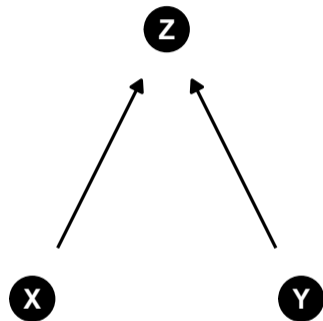
# The Collider: A Common Effect

## Collider Lemma

If there is only one path between  $X$  and  $Y$  and  $Z$  is their common effect, then  $X \perp\!\!\!\perp Y$  but  $X \not\perp\!\!\!\perp Y | Z$ .

## So what?

- ▶ This is the weird/interesting/confusing one.
- ▶ Adjust for  $Z \Rightarrow$  **spurious association** between  $X$  and  $Y$ .
- ▶  $X, Y$  indep. coins;  $Z =$  bell rings if at least one HEADS.
- ▶  $X =$  beauty,  $Y =$  talent,  $Z =$  movie star.



# The Descendant

## Descendant Lemma

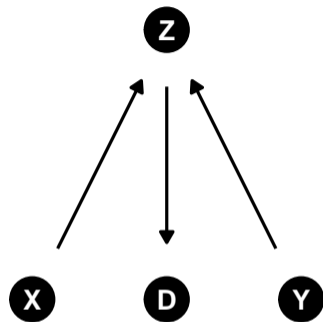
Conditioning on a descendant  $D$  of  $Z$  has the effect of *partially conditioning* on  $Z$  itself.

## Collider Corollary

In the figure,  $X \perp\!\!\!\perp Y$  but  $X \not\perp\!\!\!\perp Y | D$ .

## Discussion

- ▶ What this means depends on the situation.
- ▶ In the figure  $Z$  is a collider.
- ▶ Could also have  $Z$  as the middle node in pipe/fork.
- ▶ Pipe/fork: adjust for  $D \Rightarrow$  **partially block**  $X, Y$  path.



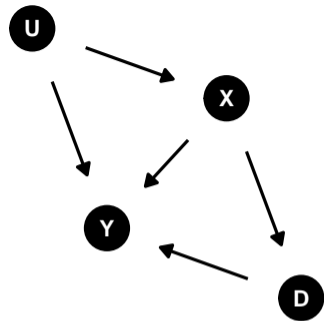
## Blocked Path

A set of nodes  $Z$  **blocks a path**  $p$  iff  $p$  contains:

1. a pipe/fork whose middle node is in  $Z$  or
2. a collider that is not in  $Z$  and has no descendants in  $Z$ .

## $d$ -Separation

If  $Z$  blocks all paths between  $X$  and  $Y$ , then  $X \perp\!\!\!\perp Y | Z$ . We say that  $X$  and  $Y$  are  **$d$ -separated** conditional on  $Z$ .



## Paths between $D$ and $U$

$$(D \rightarrow Y \leftarrow U)$$

Path I

$$(D \rightarrow Y \leftarrow X \leftarrow U)$$

Path II

$$(D \leftarrow X \rightarrow Y \leftarrow U)$$

Path III

$$(D \leftarrow X \leftarrow U)$$

Path IV

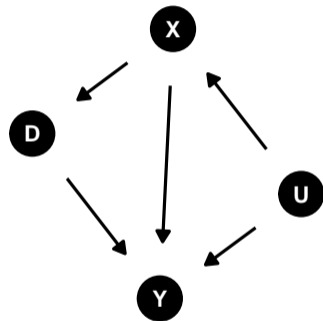
- ▶ Paths I–III already blocked:  $Y$  is a collider. Conditioning on  $X$  blocks Path IV.
- ▶ Therefore,  $D$  and  $U$  are  $d$ -separated conditional on  $X$ .

## Building and Plotting a DAG in R

Using the `ggdag` package.

```
library(ggdag)
mydag <- dagify(
  Y ~ X + U + D,
  X ~ U,
  D ~ X
)

mydag |>
  ggdag(node_size = 8, text_size = 3) +
  theme_dag()
```



## Finding Paths: Open and Closed

Using the `dagitty` package

```
library(dagitty)
paths(mydag, from = 'D', to = 'U')

## $paths
## [1] "D -> Y <- U"      "D -> Y <- X <- U" "D <- X -> Y <- U" "D <- X <- U"
##
## $open
## [1] FALSE FALSE FALSE TRUE
```

## Graph Surgery

Observational Distribution:  $\mathbb{P}(Y|X = x)$

*Actual* distribution of  $Y$  among people observed to have  $X = x$ .

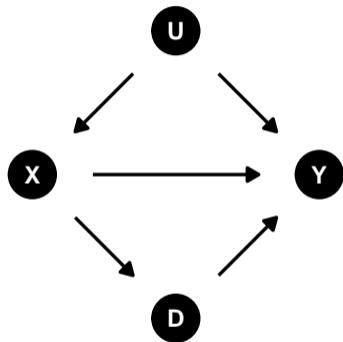
Interventional Distribution:  $\mathbb{P}(Y|do(X = x))$

Distribution of  $Y$  that that we *would obtain* if we *intervened* and set  $X = x$  for everyone.

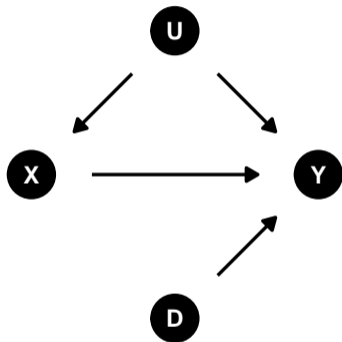
- ▶ DAG encodes observational distribution.
- ▶ Delete edges **pointing into**  $D$  to obtain  $do(D)$  interventional distribution.
- ▶ Causal effect of interest is the path from  $D$  to  $Y$  in this “modified” graph.
- ▶ This is what an experiment does!
- ▶  $ATE = \mathbb{E}(Y_1 - Y_0) = \mathbb{E}(Y|do(D = 1)) - \mathbb{E}(Y|do(D = 0))$

## Graph Surgery: Delete Edges Pointing Into $D$

Observational Distribution



Interventional Distribution



- ▶ Absent an experiment, all we have is the observational distribution.
- ▶ How can we use it to learn about the (unobserved) interventional distribution?

# Shutting Back-doors

## Back-door Paths

- ▶ Path between treatment and outcome starting with edge pointing *into* treatment.
- ▶ Noncausal: only edges pointing *out* from treatment represent causal effects.

## Intuition

- ▶ Experiments *delete* back-door paths: remove edges pointing into treatment.
- ▶ If we can't delete the back-door paths, maybe we can **block** them instead.

## Back-door Criterion

A set of nodes  $Z$  satisfies the back-door criterion relative to  $(X, Y)$  if no node in  $Z$  is a descendant of  $X$  and  $Z$  blocks every back-door path between  $X$  and  $Y$ .



## A Less Formal Statement of the Back-door Criterion

1. List all the paths that connect treatment and outcome.
2. Check which of them *open*. A path is *open* unless it contains a collider.
3. Check which of them are *back-door paths*: contain an arrow pointing at  $D$ .
4. If there are no open back-door paths, you're done. If not, look for nodes you can condition on to **block** remaining open back-door paths without opening new ones.

Of course we can only condition on *observed variables*!

# The Payoff

## Back-door Theorem

If  $Z$  satisfies the back-door criterion relative to  $(X, Y)$ , then

$$\mathbb{P}(Y = y | do(X = x)) = \sum_z \mathbb{P}(Y = y | X = x, Z = z) \mathbb{P}(Z = z)$$

## Counterfactual Interpretation

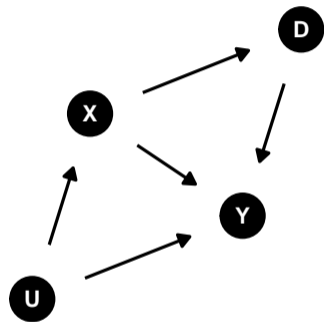
If  $Z$  satisfies the back-door criterion relative to  $(X, Y)$ , then for all  $x$   $Y_x \perp\!\!\!\perp X | Z$ .

## Translating to Potential Outcomes

- ▶ The “counterfactuals”  $Y_x$  are our potential outcomes from last lecture.
- ▶ Back-door criterion implies selection on observables assumption for  $X$  given  $Z$ .
- ▶ The formula above is nothing more than **regression adjustment**.

## Finding Adjustment Sets with dagitty

```
mydag <- dagify(  
  Y ~ X + U + D,  
  X ~ U,  
  D ~ X  
)  
adjustmentSets(mydag,  
               exposure = 'D',  
               outcome = 'Y')  
## { X }
```



## Example: Causal effect of exercise on cancer.<sup>6</sup>

### Observed

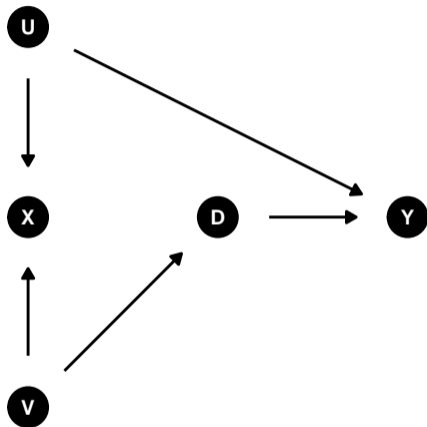
- ▶  $D$  = physical activity
- ▶  $Y$  = cervical cancer (Yes/No)
- ▶  $X$  = positive pap smear test result (Yes/No)

### Unobserved

- ▶  $U$  = pre-cancer lesion (Yes/No)
- ▶  $V$  = health-consciousness

### Story

Health-conscious  $\Rightarrow$  more physically active; more visits to doctor. Should we adjust for  $X$ ?



<sup>6</sup>Adapted from [Hernan & Robins \(2020\)](#) Section 7.4.

## Exercise / Cancer Example Continued

- ▶  $X$  is a **collider**: it *blocks* the back-door path between  $D$  and  $Y$  through  $(U, V)$ .
- ▶ Adjusting for  $X$  *opens* this blocked path, so  $X$  is a **bad control**.
- ▶ Back door criterion is satisfied with  $Z = \emptyset$ : don't condition on *anything*!

```
library(dagitty)
library(ggdag)
dagify(Y ~ D + U, D ~ V, X ~ U + V) |>
  paths(from = 'D', to = 'Y')

## $paths
## [1] "D -> Y"           "D <- V -> X <- U -> Y"
##
## $open
## [1] TRUE FALSE
```

## Futher Reading on Graphical Causal Models

- ▶ Shalizi (2021) - Advanced Data Analysis from an Elementary Point of View Chapters 19–22.
- ▶ Cinelli, Forney & Pearl (2022) - A Crash Course in Good and Bad Controls
- ▶ Pearl, Glymour & Jewell (2016) - Causal Inference in Statistics: A Primer
- ▶ Pearl (2009) - Causality: Models, Reasoning & Inference (2nd ed)
- ▶ Huntington-Klein (2022) - The Effect
- ▶ Pearl & Mackenzie (2018) - The Book of Why
- ▶ Huntington-Klein (2022) - Pearl before Economists
- ▶ Traag & Waltman (2022) - Causal Foundations of Bias, Disparity and Fairness
- ▶ Heiss - Causal Inference and this blog post on the *do*-calculus.